

# EnRich 2025

## Team Information

30 June – 4 July 2025, Zwentendorf, Austria

Picture(s) of vehicle(s):



Name(s) of vehicle(s):

- Husky ROV (equipped with a UR5 manipulator)
- Unitree Go2 robot dog
- Agipix\_v2 drone

Picture of team leader:



Name of team leader: Prof. Dr. Tomi Westerlund

Team Name: RAICAM

Team E-mail: [tovewe@utu.fi](mailto:tovewe@utu.fi)

Logo:



Website: <https://raicam.eu/>

Country: Finland

Institution/Company: University of Turku

Address: Vesilinnantie 5  
20500  
Turku, Finland

Telephone: +358 50 343 7684

**Return form to: [enrich@fkf.fraunhofer.de](mailto:enrich@fkf.fraunhofer.de)**

# EnRich 2025

## Team Information

30 June – 4 July 2025, Zwentendorf, Austria

Team Description: RAICAM is a project involving a group of PhD students working on the next generation of mobile robots for the inspection and maintenance of nuclear facilities, as part of the EU-funded MSCA Doctoral Training Network. Our goal is to develop a multi-domain, multi-agent robotic system for sample retrieval, and we aim to demonstrate the real-world applicability of our work by participating in EnRich 2025.

Sponsor(s): Our team is supported by the European Commission's Marie Skłodowska-Curie Actions (MSCA), project RAICAM (GA 101072634).

Selection of scenario(s):

- 3D Mapping
- Radiation Mapping
- Manipulation
- Search and Rescue
- UAV Mapping
- \*EOD/IED

Date of arrival at site: 27 June 2025 (Friday)

Proof of citizenship: **A copy of team leader passport will do (will not be published)**

Please do not forget to submit the Team Application, Insurance Certificate and TeamMembershipRoster.

**Return form to: [enrich@fkf.fraunhofer.de](mailto:enrich@fkf.fraunhofer.de)**